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// THIS IS THE TEXT SOURCE CODE OF file: Auto_House.ino

/*
Arduino MICRO software to operate an automated model train home.

Written by: Bruce Kingsley
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Version: 1.0.0

Revision Note:

    1.0.0    05-JUL-2014 RBK    First release.

*/

void LightingEffects(void);
void Effect(void);
void WomanServoEffects(void);

#include <Servo.h>

#define NUM_OF_FADE_LIGHTS    7

#define LIGHT_TV              0
#define LIGHT_FRT_PORCH      1
#define LIGHT_LIVE_ROOM      2
#define LIGHT_SIDE_ROOM      3
#define LIGHT_KITCHEN        4
#define LIGHT_FRT_BEDRM      5
#define LIGHT_RER_BEDRM      6

#define EFFECT_DOOR_BELL_LIGHT_PIN    8
#define EFFECT_SOUND_PIN              12
#define EFFECT_WOMAN_SERVO_PIN        9

Servo WomanServoObject;           // create servo object to control a servo that rotates woman
in living room.
int WomanServoCommand;           // The last command sent to the woman servo (before mapping).
int WomanServoCommandPWMValue;   // The last value sent to the Servo Object.
unsigned long WomanServoNextOutput; // The next time the servo output should be sent out.
#define SERVO_PWM_MIN    10       // The smallest PWM command we want to send to the servo.
#define SERVO_PWM_MAX    160      // The largest PWM command we want to send to the servo.
#define SERVO_VELOCITY  20       // The rate of rotation in milli-seconds. Bigger the number,
slower the rotation.

int FadeLightPorts[NUM_OF_FADE_LIGHTS];           // Store the digital PWM ports the lights are
connect to.
bool FadeLightOnCommand[NUM_OF_FADE_LIGHTS];     // Is this light to be turned on or off.
bool FadeLightOn[NUM_OF_FADE_LIGHTS];            // Is this light on or off.
int LightFadeValue[NUM_OF_FADE_LIGHTS];          // The PWM value while in fading.
bool LightInFade[NUM_OF_FADE_LIGHTS];            // Light is currently fading.

unsigned long NextTelevisionFlicker; // The time the TV light level is changed.
#define TV_FLICKER_TIME 100          // How many milliseconds between TV flickers.

#define NUM_OF_SEQUENCES    15

int CurrentSequence;
unsigned long NextSequenceTime;
unsigned long SequenceDuration; //Sequence in milliseconds

void setup()
{
    int i;

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// Setup the ports used for fade-able lights.

FadeLightPorts[LIGHT_TV] = 13; // The TV uses the PWM digital port 13.
FadeLightPorts[LIGHT_FRT_PORCH] = 10; // The front porch uses the PWM digital port 10.
FadeLightPorts[LIGHT_LIVE_ROOM] = 11; // The living room uses the PWM digital port 9.
FadeLightPorts[LIGHT_SIDE_ROOM] = 6; // The side rrom uses the PWM digital port 6.
FadeLightPorts[LIGHT_KITCHEN] = 5; // The kitchen uses the PWM digital port 5.
FadeLightPorts[LIGHT_FRT_BEDRM] = 3; // The front bedroom uses the PWM digital port 3.
FadeLightPorts[LIGHT_RER_BEDRM] = 4; // The rear bedroom uses the PWM digital port 4.

for(i = 0; i!= NUM_OF_FADE_LIGHTS; i++)
{
  pinMode(FadeLightPorts[i], OUTPUT);
  analogWrite(FadeLightPorts[i], 255); //Hi value turns lights off.
  FadeLightOnCommand[i] = false;
  FadeLightOn[i] = false;
  LightFadeValue[i] = 255;
  LightInFade[i] = false;
}

//Setup the effect ports
pinMode(EFFECT_DOOR_BELL_LIGHT_PIN, OUTPUT);
pinMode(EFFECT_SOUND_PIN, OUTPUT);

//Setup woman servo
WomanServoCommand = 125; // Start off with woman in the middle of rotation.
WomanServoObject.attach(EFFECT_WOMAN_SERVO_PIN); // Attaches the servo to the servo object.
i = map(WomanServoCommand, 0, 255, SERVO_PWM_MIN, SERVO_PWM_MAX); // scale it to use it with
the servo.
WomanServoCommandPWMValue = i;
WomanServoObject.write(i);
WomanServoNextOutput = millis();

NextTelevisonFlicker = millis();

// Turn sound off
digitalWrite(EFFECT_SOUND_PIN, HIGH);

// Turn door bell button off
digitalWrite(EFFECT_DOOR_BELL_LIGHT_PIN, HIGH);

// Setup sequences
CurrentSequence = 1;
SequenceDuration = 1000;

NextSequenceTime = millis();
}

void loop()
{
  Effects();
  delay(1);

  if(millis() < NextSequenceTime) { return; } // If not time for next sequence, return from
loop.

  switch(CurrentSequence)
  {
    case 1:
      digitalWrite(EFFECT_DOOR_BELL_LIGHT_PIN, LOW); // Turn on door bell button.
      digitalWrite(EFFECT_SOUND_PIN, HIGH);
      delay(50);
      digitalWrite(EFFECT_SOUND_PIN, LOW);
      FadeLightOnCommand[LIGHT_FRT_BEDRM] = true;
      SequenceDuration = 15288;
      break;
  }
}

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case 2:
  FadelightOnCommand[LIGHT_RER_BEDRM] = true;
  SequenceDuration = 712;
  break;

case 3:
  FadelightOnCommand[LIGHT_TV] = true;
  WomanServoCommand = 250; // Face the TV
  SequenceDuration = 16167;
  break;

case 4:
  FadelightOnCommand[LIGHT_KITCHEN] = true;
  FadelightOnCommand[LIGHT_TV] = false;
  SequenceDuration = 1383;
  break;

case 5:
  FadelightOnCommand[LIGHT_SIDE_ROOM] = true;
  SequenceDuration = 14451;
  break;

case 6:
  FadelightOnCommand[LIGHT_LIVE_ROOM] = true;
  WomanServoCommand = 125; // Face the Man
  SequenceDuration = 1380;
  break;

case 7:
  SequenceDuration = 10170;
  break;

case 8:
  FadelightOnCommand[LIGHT_FRT_PORCH] = true;
  WomanServoCommand = 0; // Face the Door
  SequenceDuration = 8940;
  break;

case 9:
  FadelightOnCommand[LIGHT_FRT_PORCH] = false;
  SequenceDuration = 964;
  break;

case 10: // Start of goodnight
  FadelightOnCommand[LIGHT_SIDE_ROOM] = false;
  SequenceDuration = 2298;
  break;

case 11:
  FadelightOnCommand[LIGHT_RER_BEDRM] = false;
  SequenceDuration = 2298;
  break;

case 12:
  FadelightOnCommand[LIGHT_KITCHEN] = false;
  SequenceDuration = 2298;
  break;

case 13:
  FadelightOnCommand[LIGHT_LIVE_ROOM] = false;
  SequenceDuration = 2298;
  break;

case 14:
  FadelightOnCommand[LIGHT_FRT_BEDRM] = false;
  SequenceDuration = 15000;
  break;
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    case 15:
        digitalWrite(EFFECT_DOOR_BELL_LIGHT_PIN, HIGH); // Turn off door bell button.
        SequenceDuration = 5000;
        break;

    }

    //Setup for the next sequence
    NextSequenceTime = millis() + SequenceDuration;
    CurrentSequence++;
    if(CurrentSequence == NUM_OF_SEQUENCES + 1) { CurrentSequence = 1; } // If at the end, start
all over.

    return;
}

void Effects(void)
{
    // This function fades a light on or off
    int i;

    TelevisionEffect(); // If television is on, create a flicker effect.
    WomanServoEffects();

    for(i = 0; i != NUM_OF_FADE_LIGHTS; i++)
    {
        if(i != LIGHT_TV) // We handle the TV a different way.
        {
            if(FadeLightOn[i] != FadeLightOnCommand[i]) // The light command has changed.
            {
                FadeLightOn[i] = FadeLightOnCommand[i];
                LightInFade[i] = true;
                if(FadeLightOn[i] == true) { LightFadeValue[i] = 255; } else { LightFadeValue[i] =
0; }
            }

            if(LightInFade[i] == true) // We're in the transistion of turning a light on or off.
            {
                if(FadeLightOn[i] == true)
                {
                    LightFadeValue[i]--;
                    if(LightFadeValue[i] == 0) { LightInFade[i] = false; }
                }
                else
                {
                    LightFadeValue[i]++;
                    if(LightFadeValue[i] == 255) { LightInFade[i] = false; }
                }

                analogWrite(FadeLightPorts[i], LightFadeValue[i]); // Write new PWM value.
            }
        }
    }

    return;
}

void TelevisionEffect(void)
{
    int TVLEDCommand;
    if(FadeLightOnCommand[LIGHT_TV] == false)
    {
        analogWrite(FadeLightPorts[LIGHT_TV], 255); // Remember, we need a hi vaue to turn a light
off.
    }
    return;
}

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    }

    if(millis() < NextTelevisonFlicker) { return; } // If not ready to change TV brightness,
return.

    TVLEDCommand = random(0, 150);
    analogWrite(FadeLightPorts[LIGHT_TV], TVLEDCommand);
    NextTelevisonFlicker = millis() + TV_FLICKER_TIME;

    return;
}

void WomanServoEffects(void)
{

    int CommandMapped;

    CommandMapped = map(WomanServoCommand, 0, 255, SERVO_PWM_MIN, SERVO_PWM_MAX);

    if(CommandMapped != WomanServoCommandPWMValue)
    {
        if(millis() < WomanServoNextOutput) { return; }
        WomanServoNextOutput = millis() + SERVO_VELOCITY;

        if(CommandMapped > WomanServoCommandPWMValue) // Do we need to go CW or CCW?
        {
            WomanServoCommandPWMValue++;
        }
        else
        {
            WomanServoCommandPWMValue--;
        }

        WomanServoObject.write(WomanServoCommandPWMValue); // Send incremental command to servo's
PWM.
    }

    return;
}

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